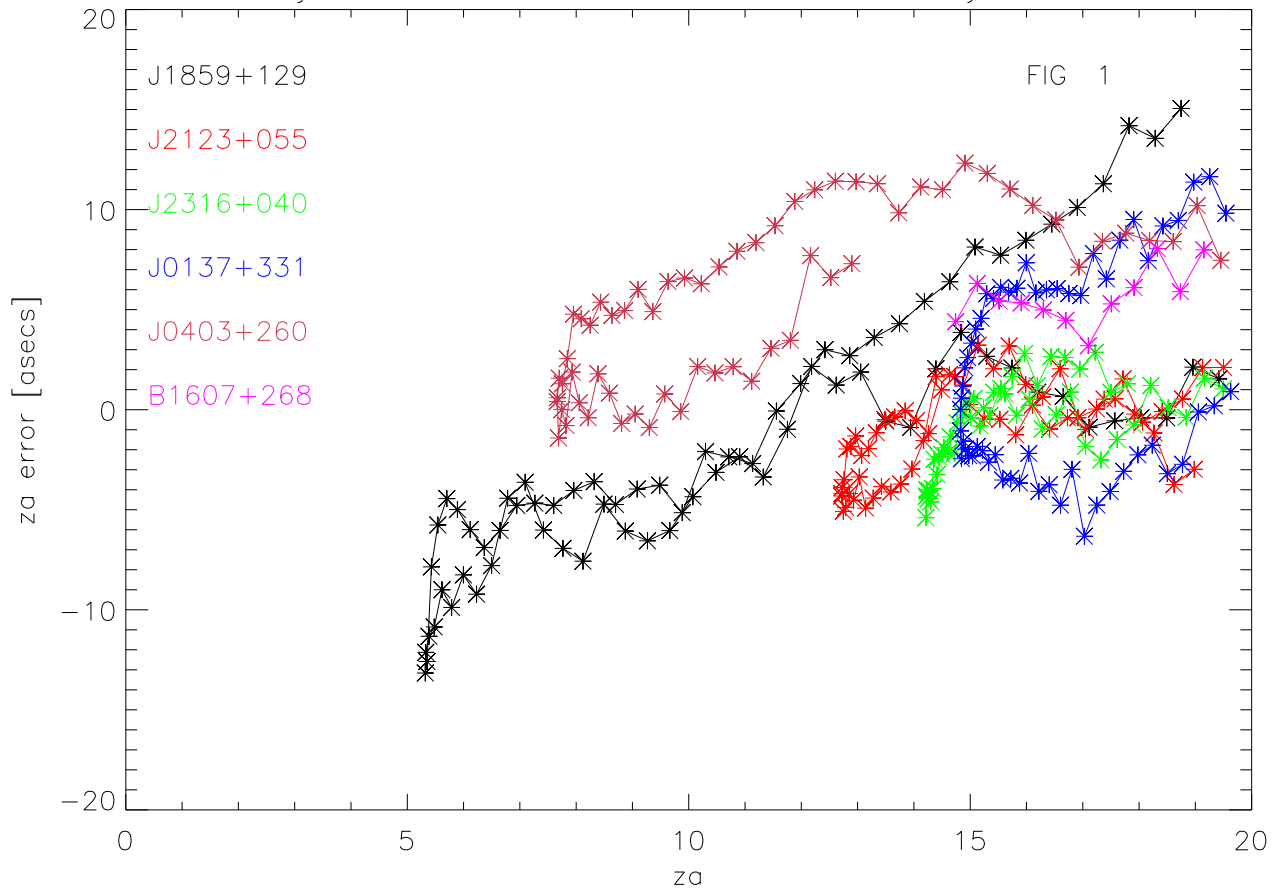
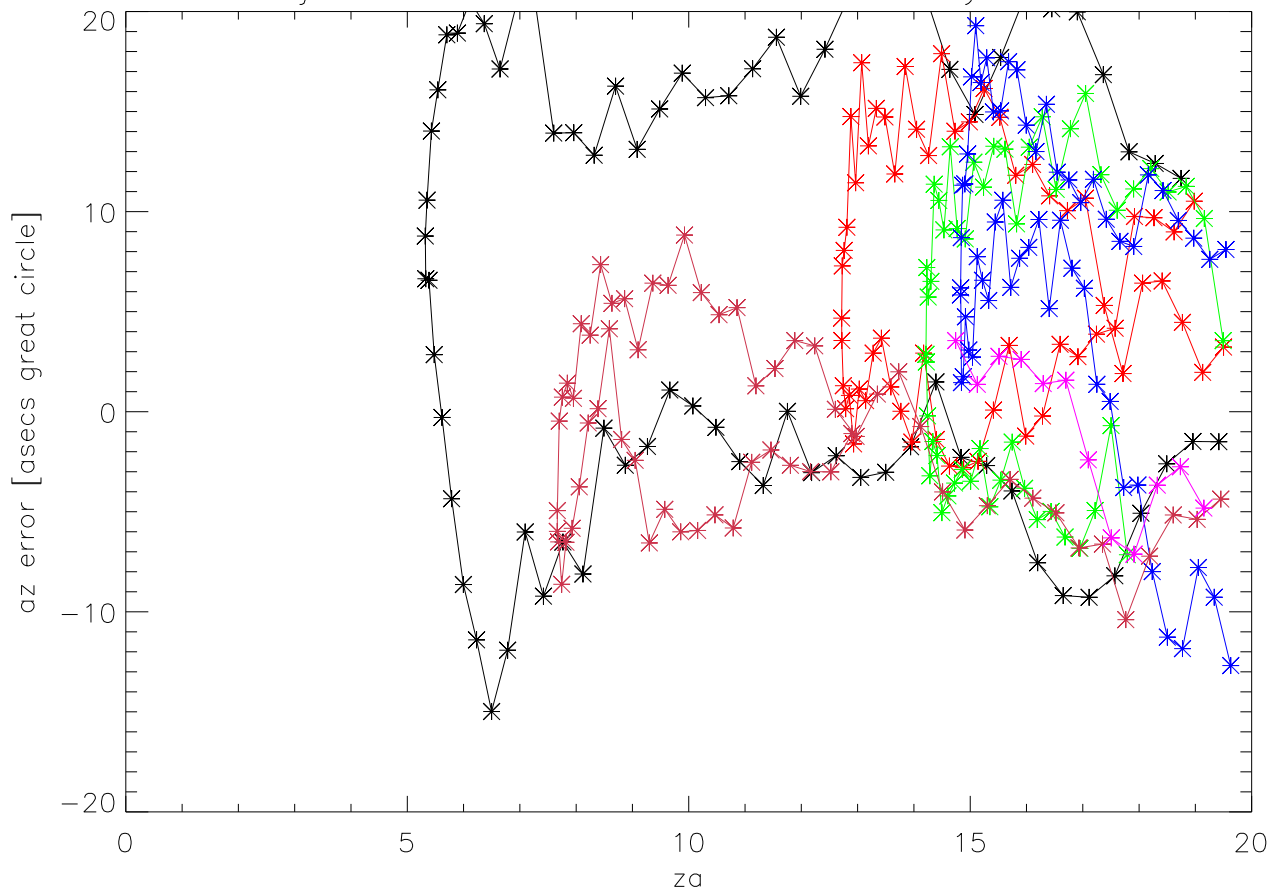


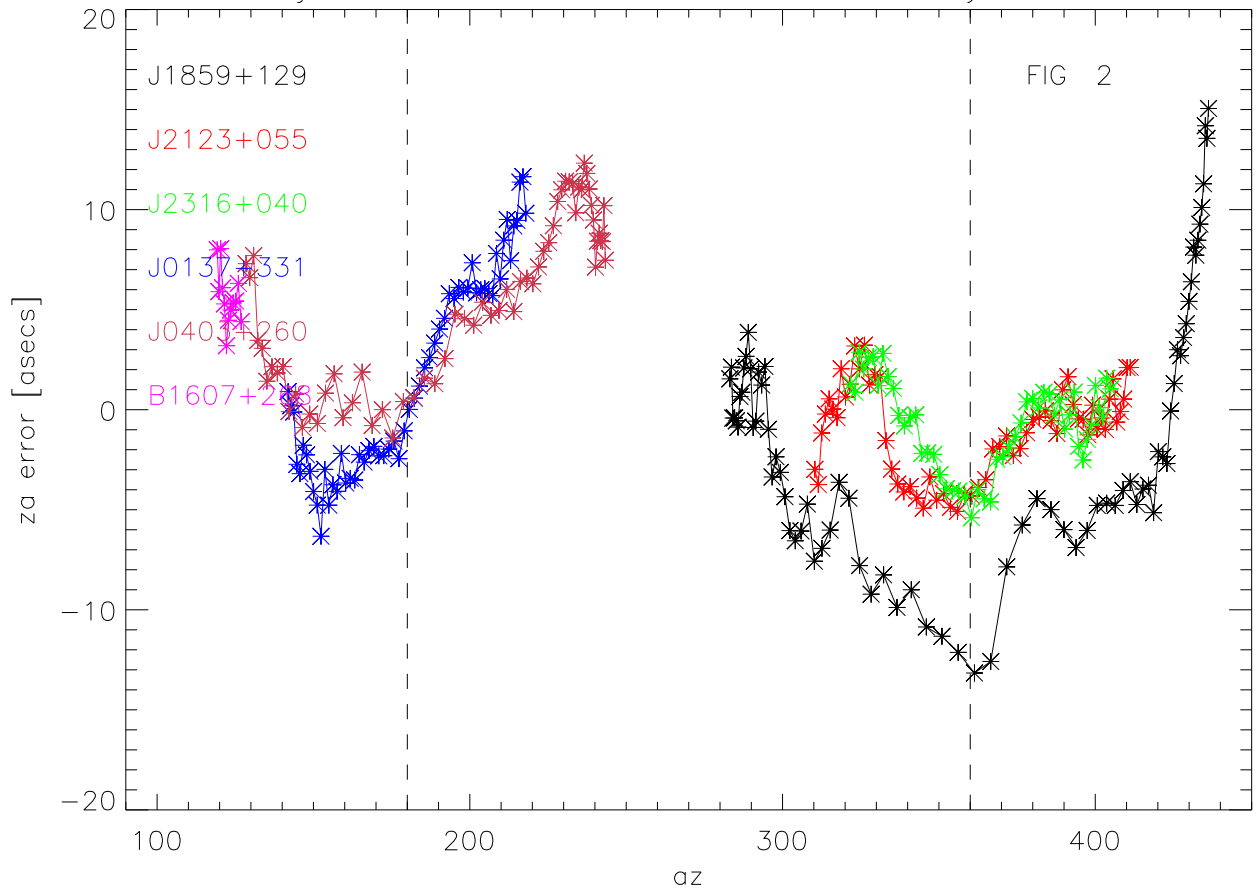
30jul01 sbn. Za error vs za after tertiary motors



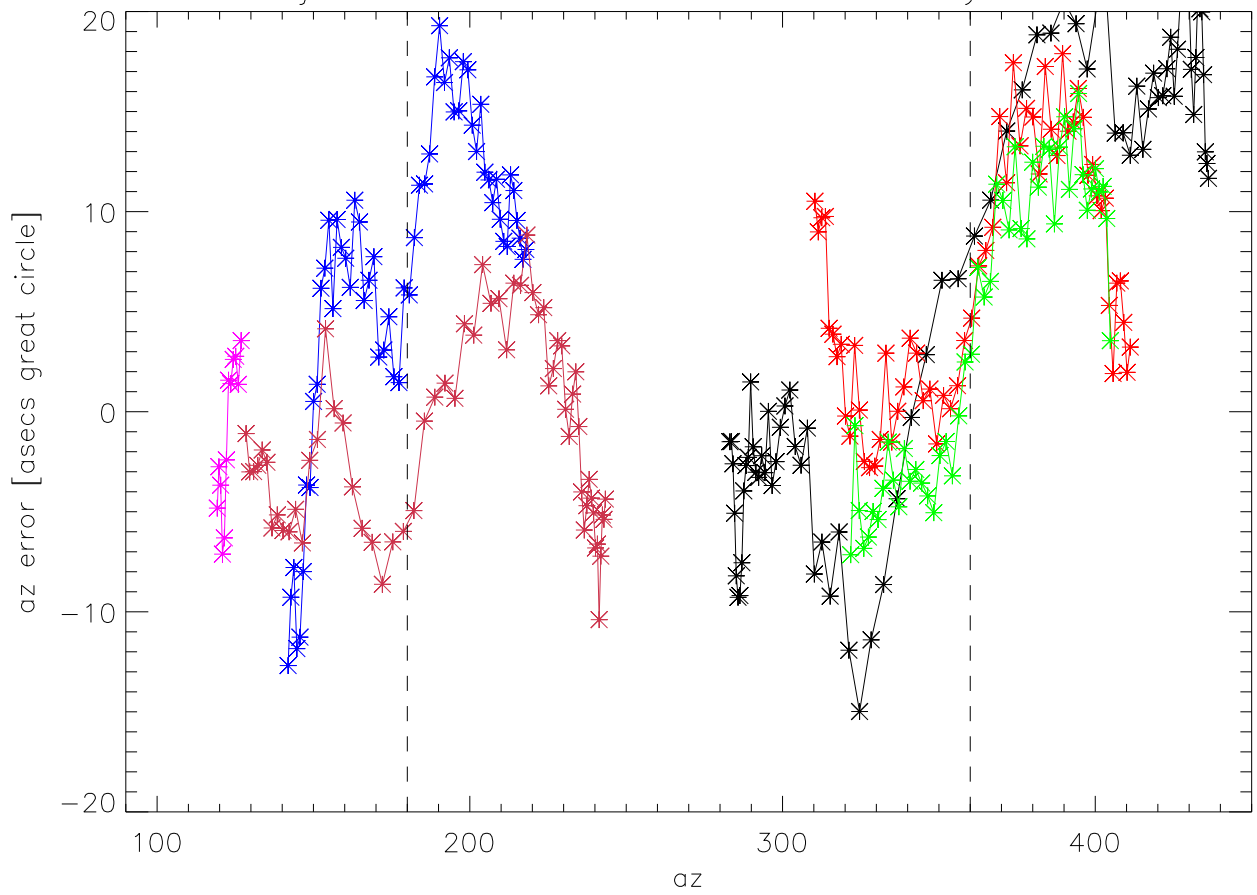
30jul01 sbn. Az error vs za after tertiary motors



30jul01 sbn. Za error vs az after tertiary motors



30jul01 sbn. Az error vs az after tertiary motors



J1859+129
 J1859+129
 J1859+129
 J1859+129
 J1859+129
 J1859+129

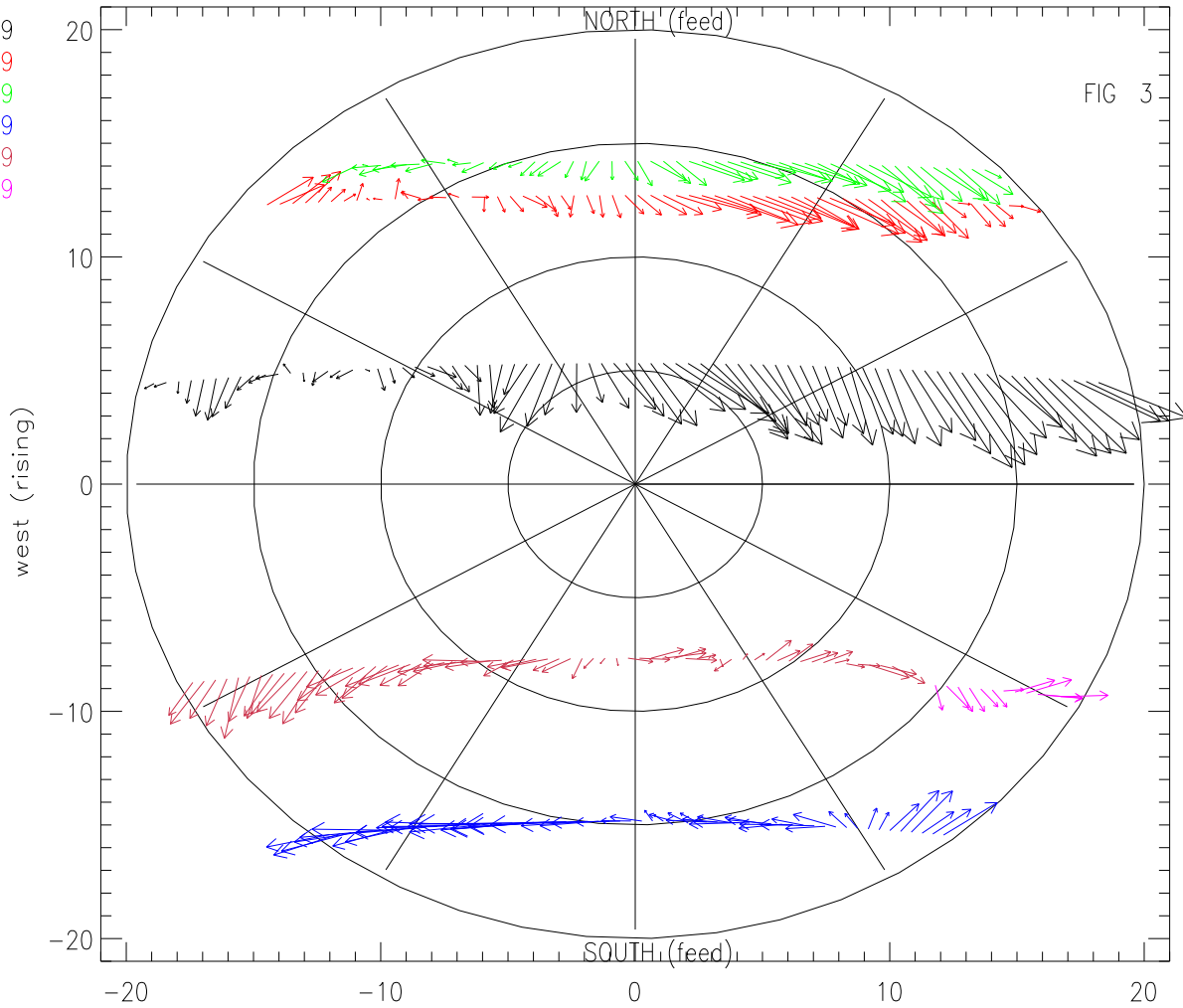
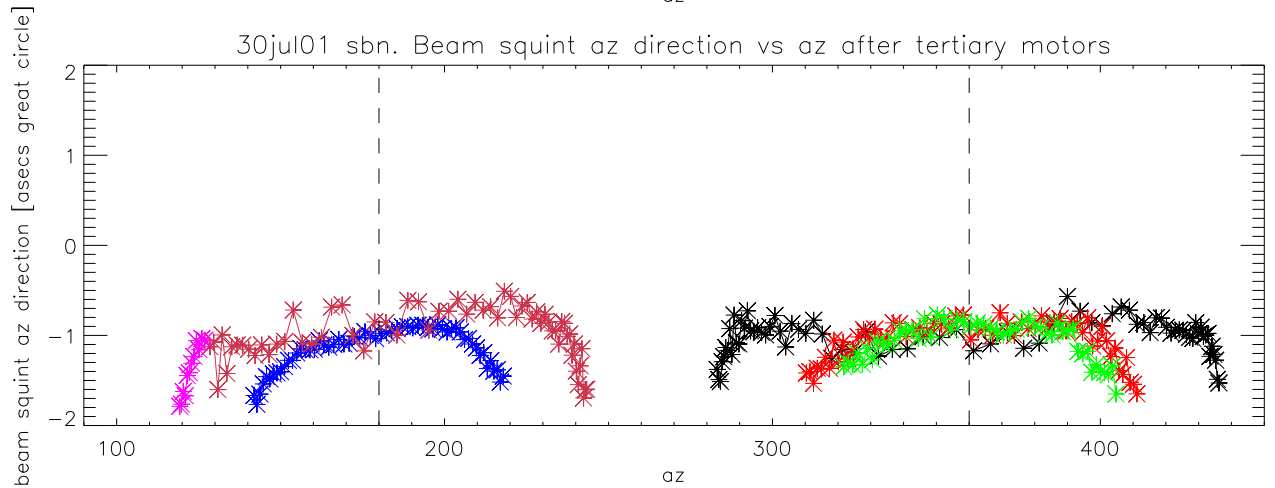
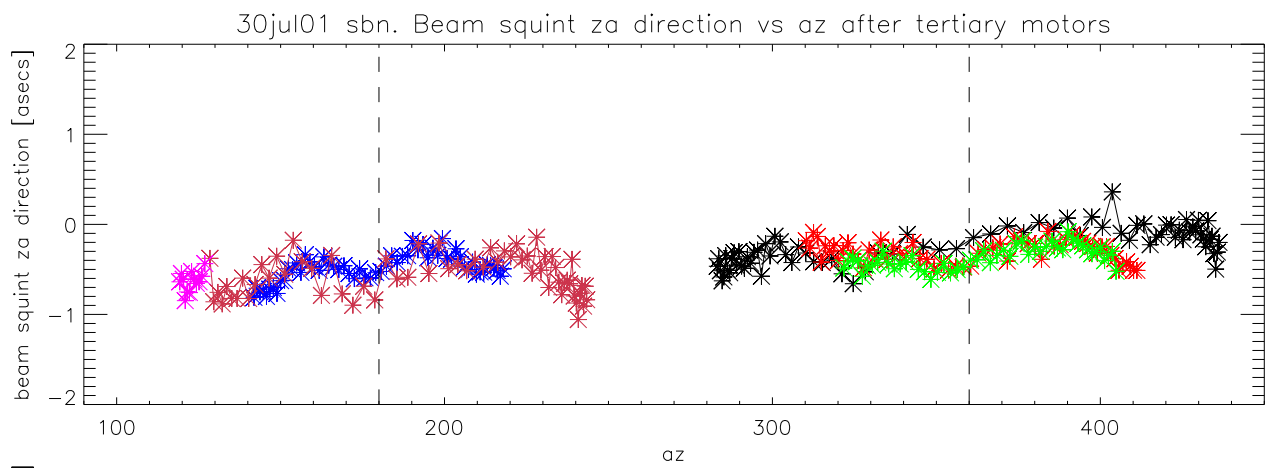
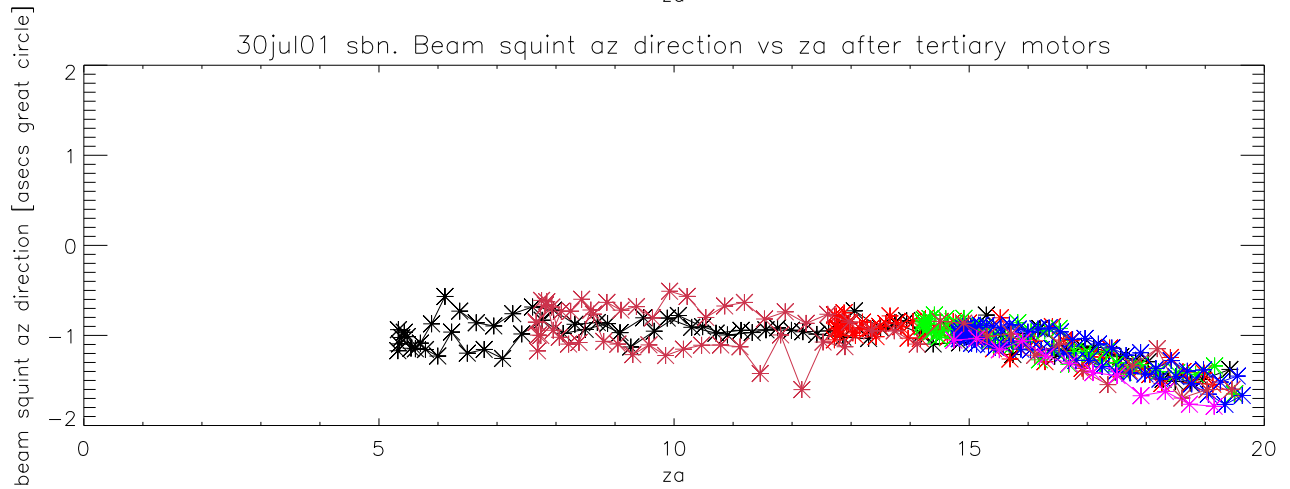
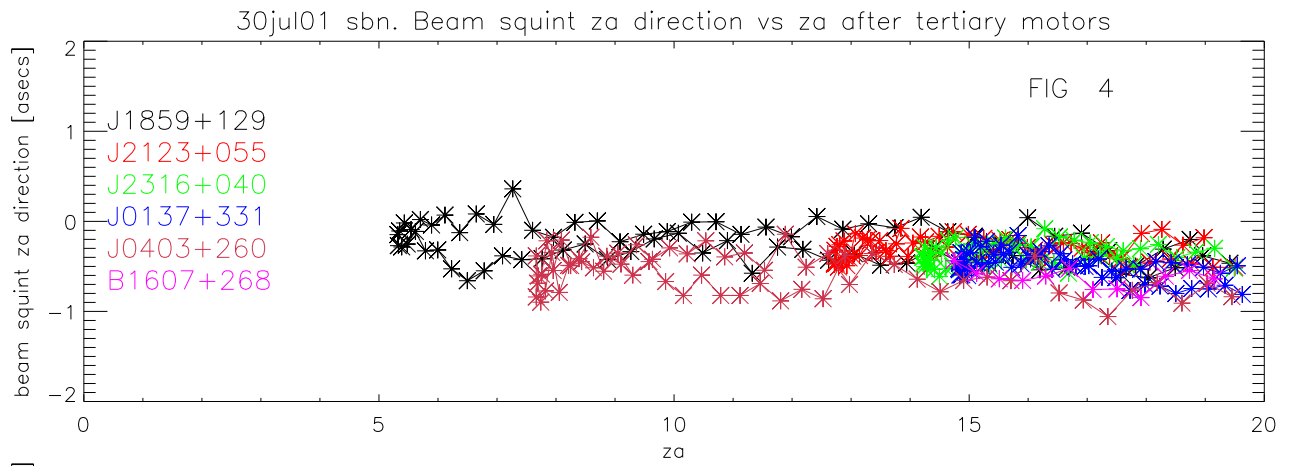


FIG 3

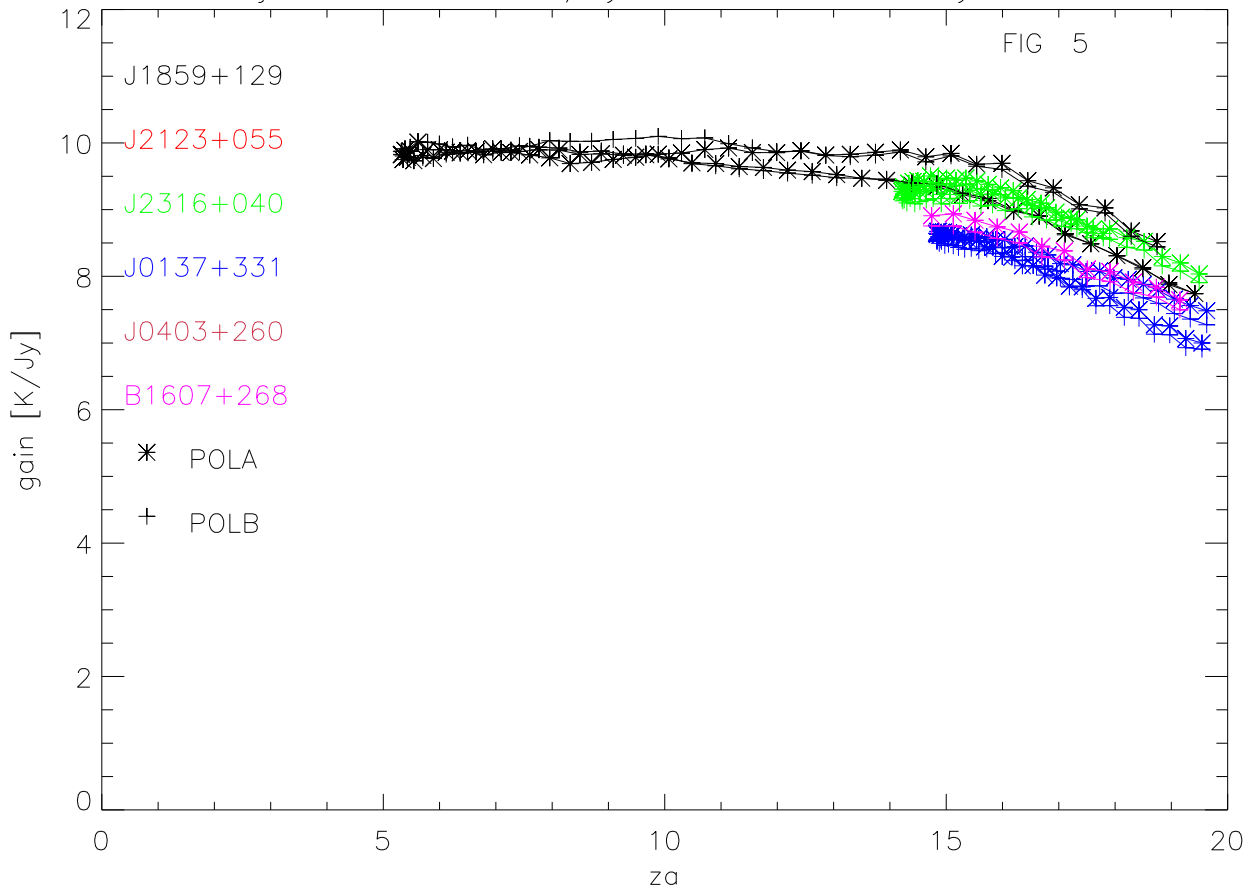
pnt Error 30jul01 vs az,za
 1 div= 5.00asecs

errors each 5.0deg

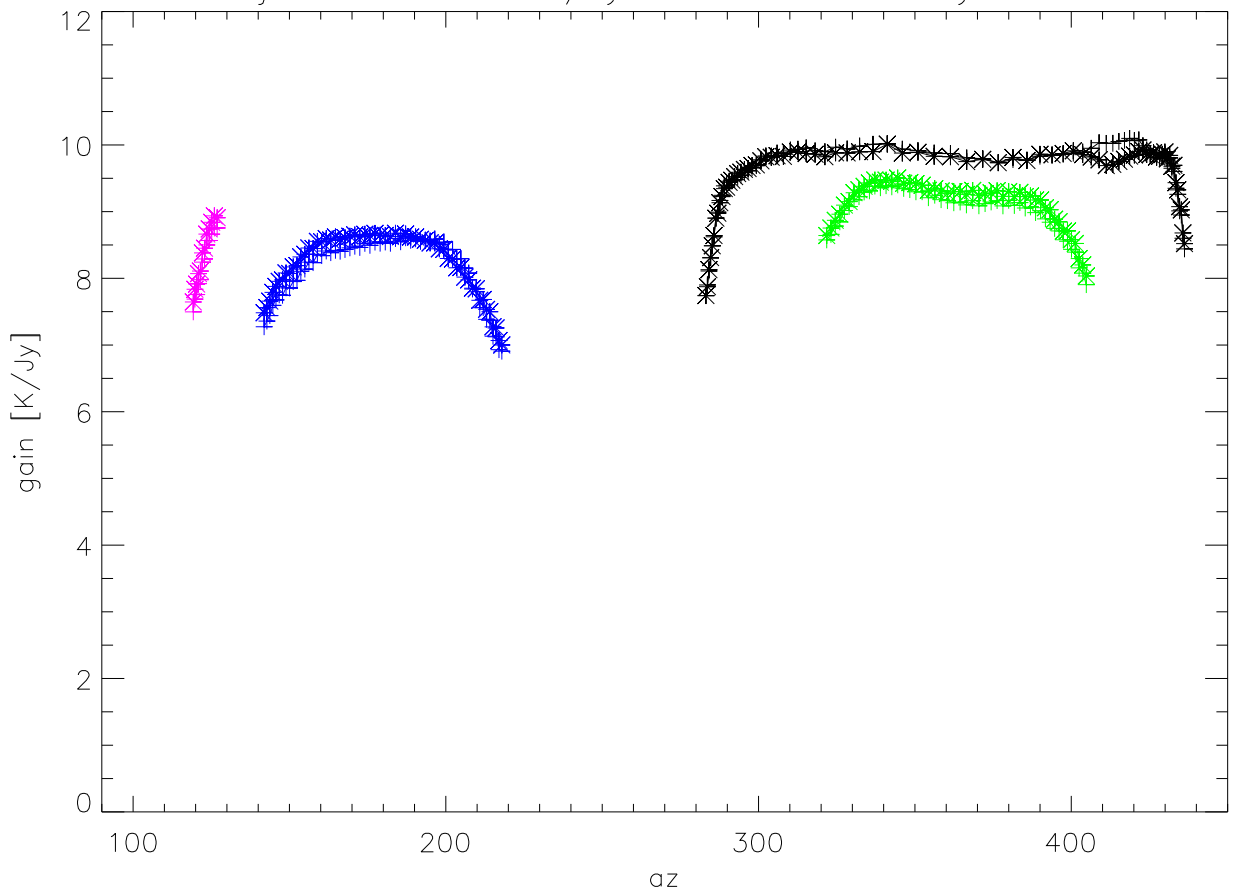
za	max	avg	rms
all	24.3	9.5	5.3
5	0.0	0.0	0.0
10	21.4	10.2	5.8
15	24.3	8.7	5.4
20	22.5	9.8	5.0



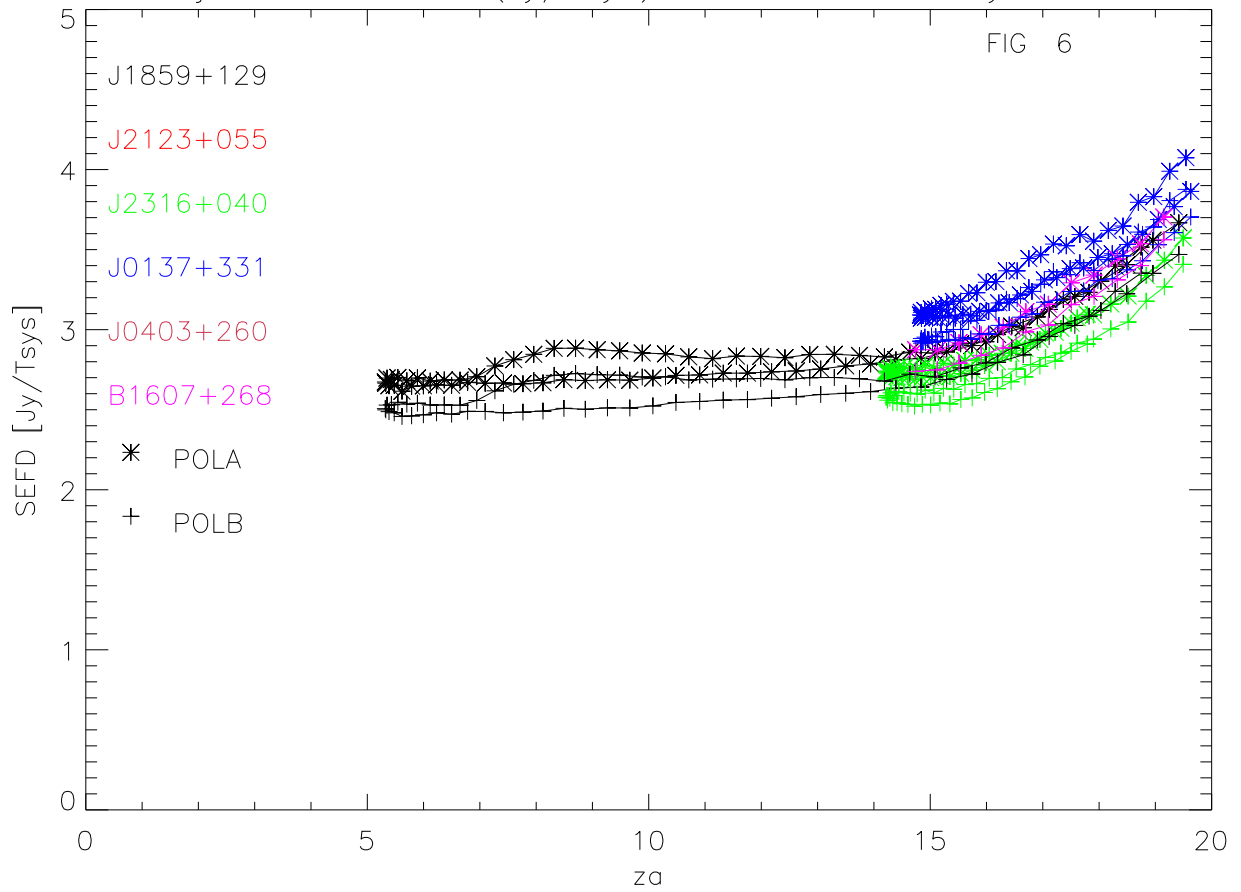
30jul01 sbn. Gain K/Jy vs za after tertiary motors



30jul01 sbn. Gain K/Jy vs az after tertiary motors



30jul01 sbn. SEFD (Jy/Tsys) vs za after tertiary motors



30jul01 sbn. SEFD (Tsys/Jy) vs az after tertiary motors

