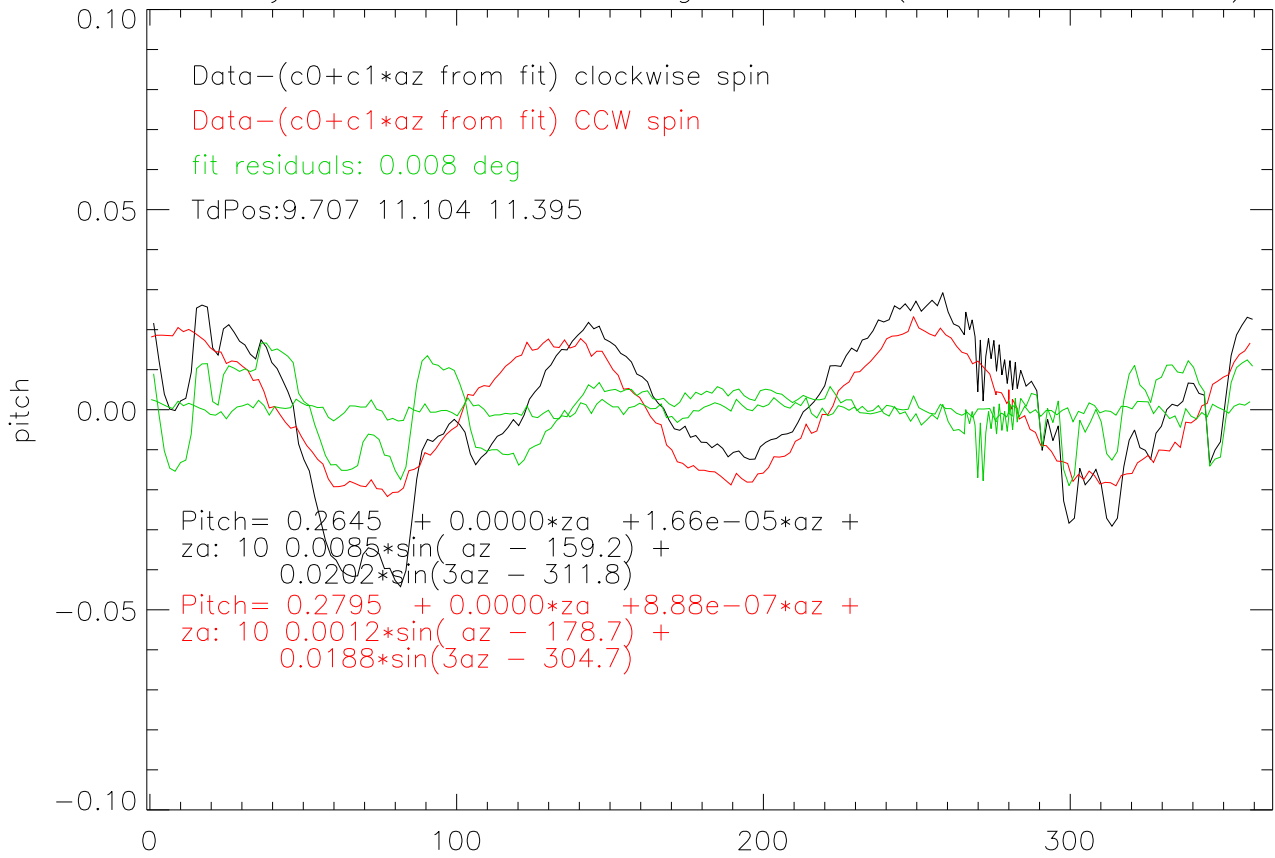


24may12 tilt sensor az swings PITCH - (c0+c1*az from fit)



24may12 tilt sensor az swings Roll - (c0+c1*az from fit)

