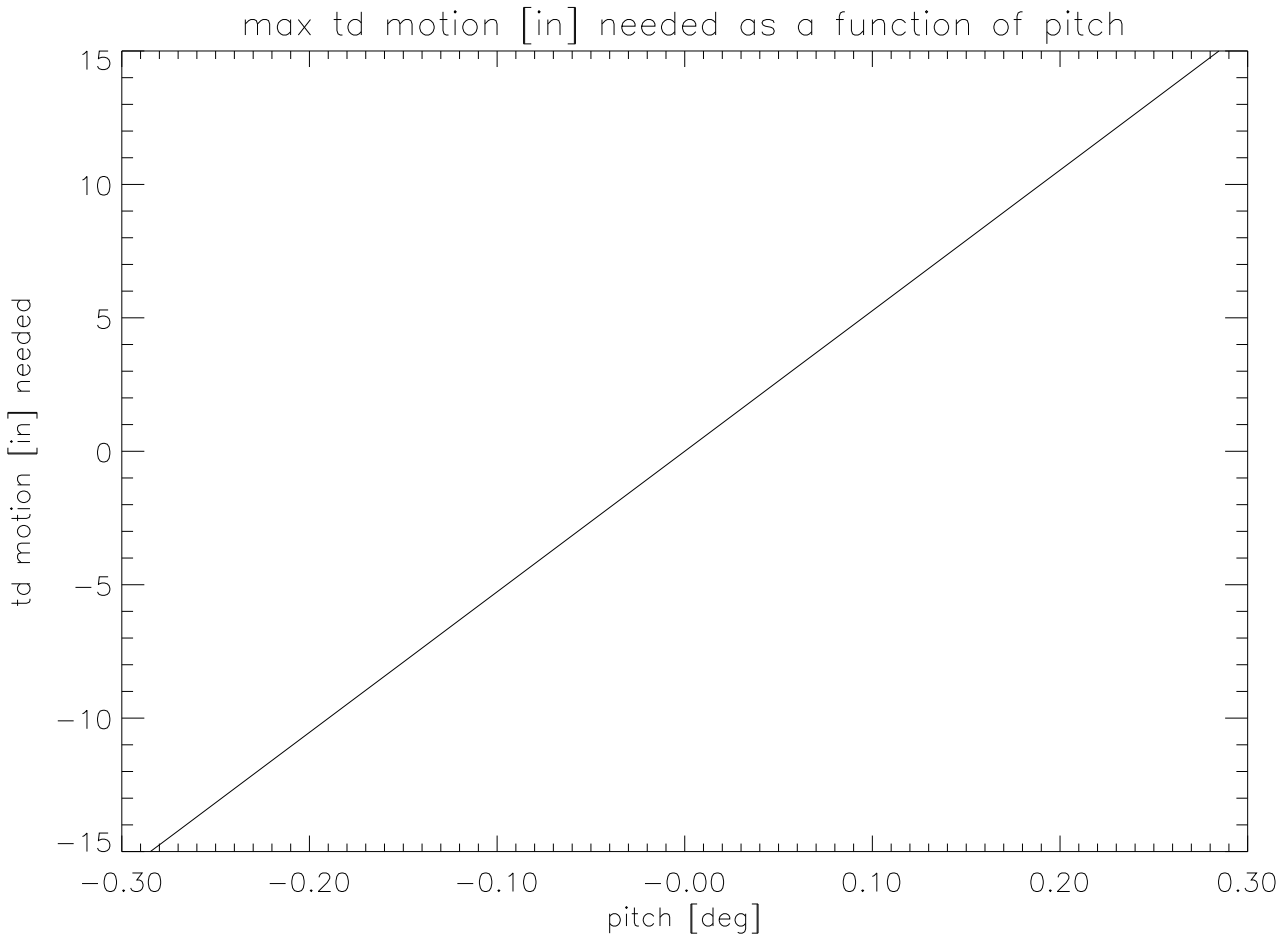
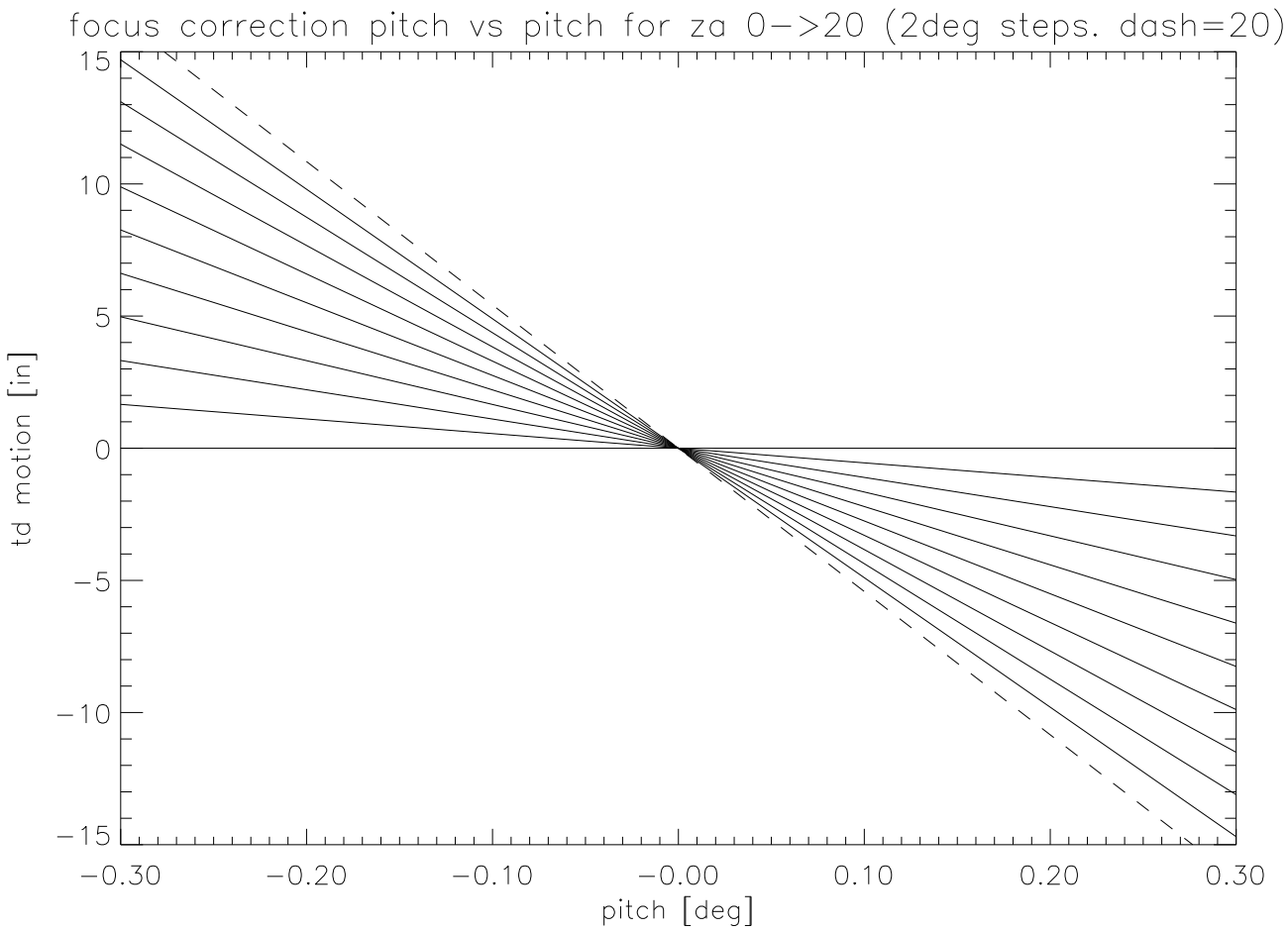

max td motion [in] needed as a function of pitch
td motion [in] needed
pitch [deg]
15
10
5
0
−5
−10
−15
−0.30
−0.20
−0.10
−0.00
0.10
0.20
0.30


focus correction pitch vs pitch for za 0−>20 (2deg steps. dash=20)
td motion [in]
pitch [deg]
15
10
5
0
−5
−10
−15
−0.30
−0.20
−0.10
−0.00
0.10
0.20
0.30