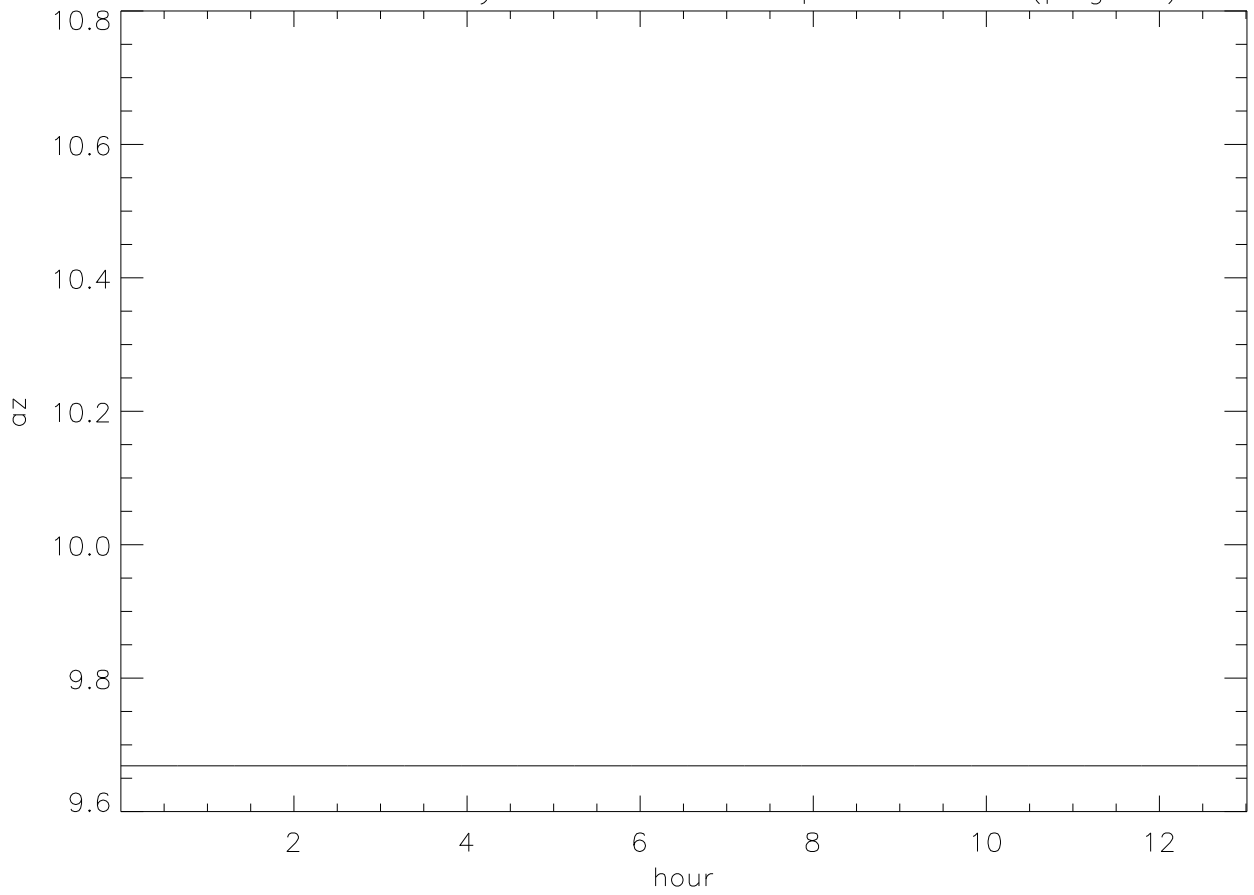
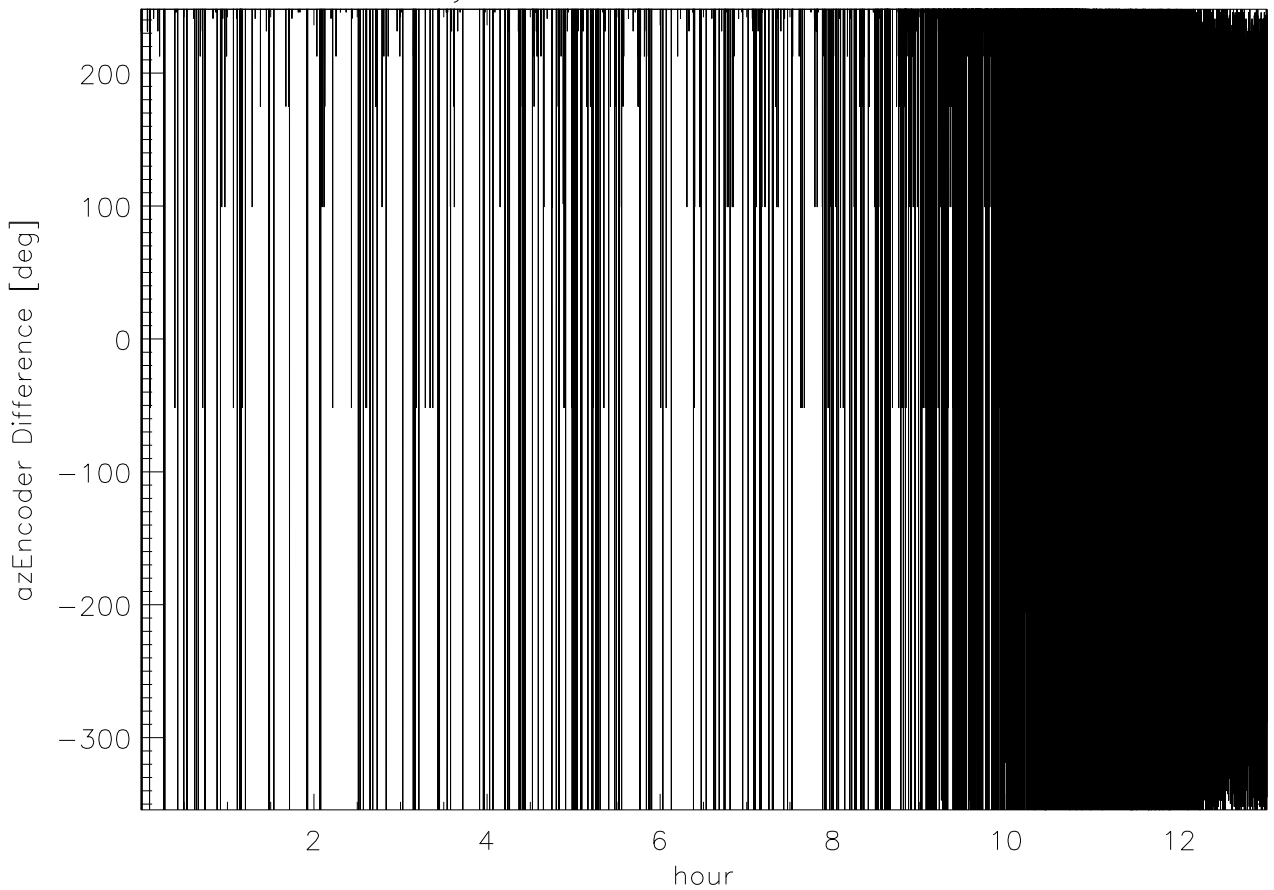


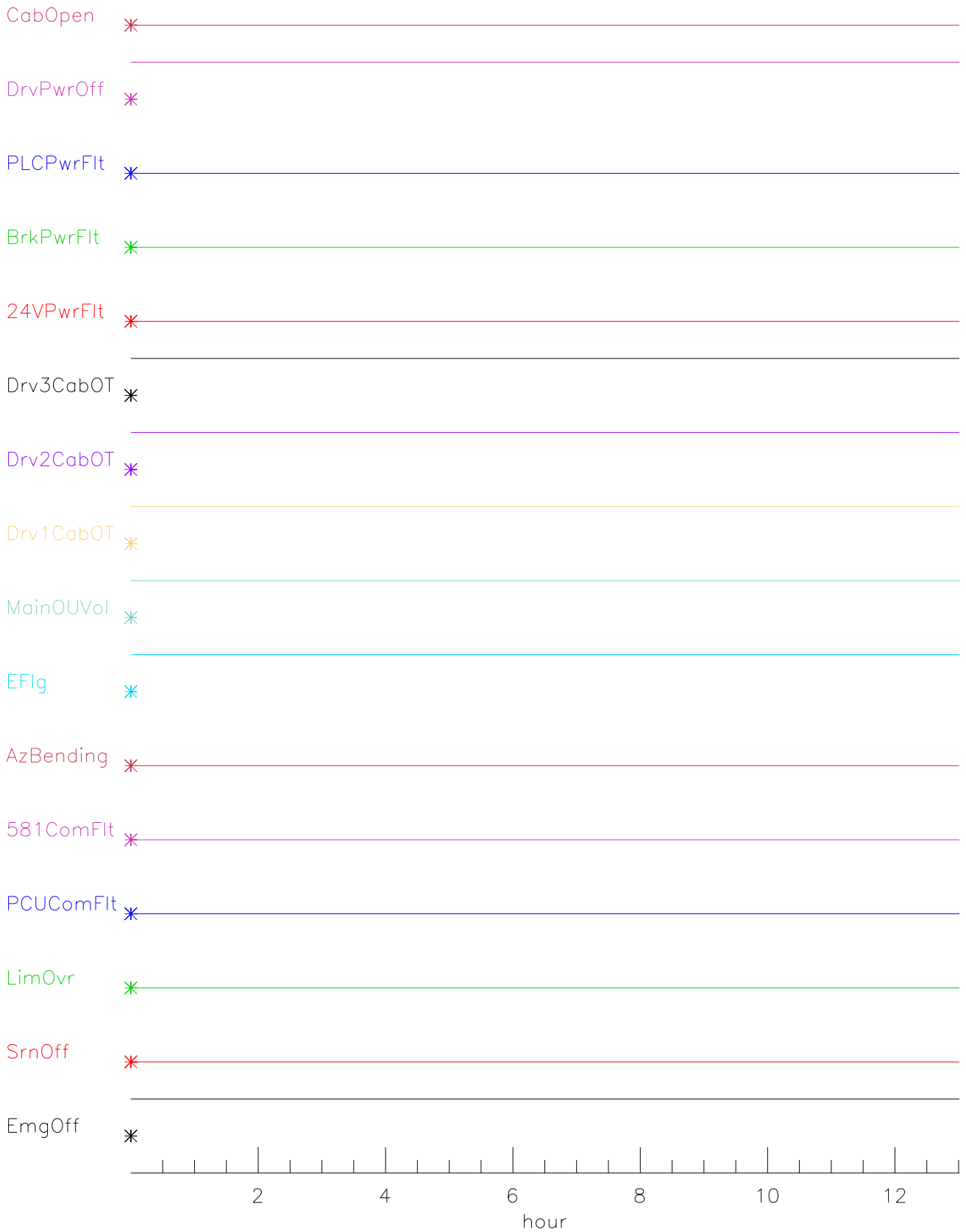
Azimuth summary for: 201103 az pos vs hour (page 1)



Azimuth summary for: 201103 az encoder difference vs hour



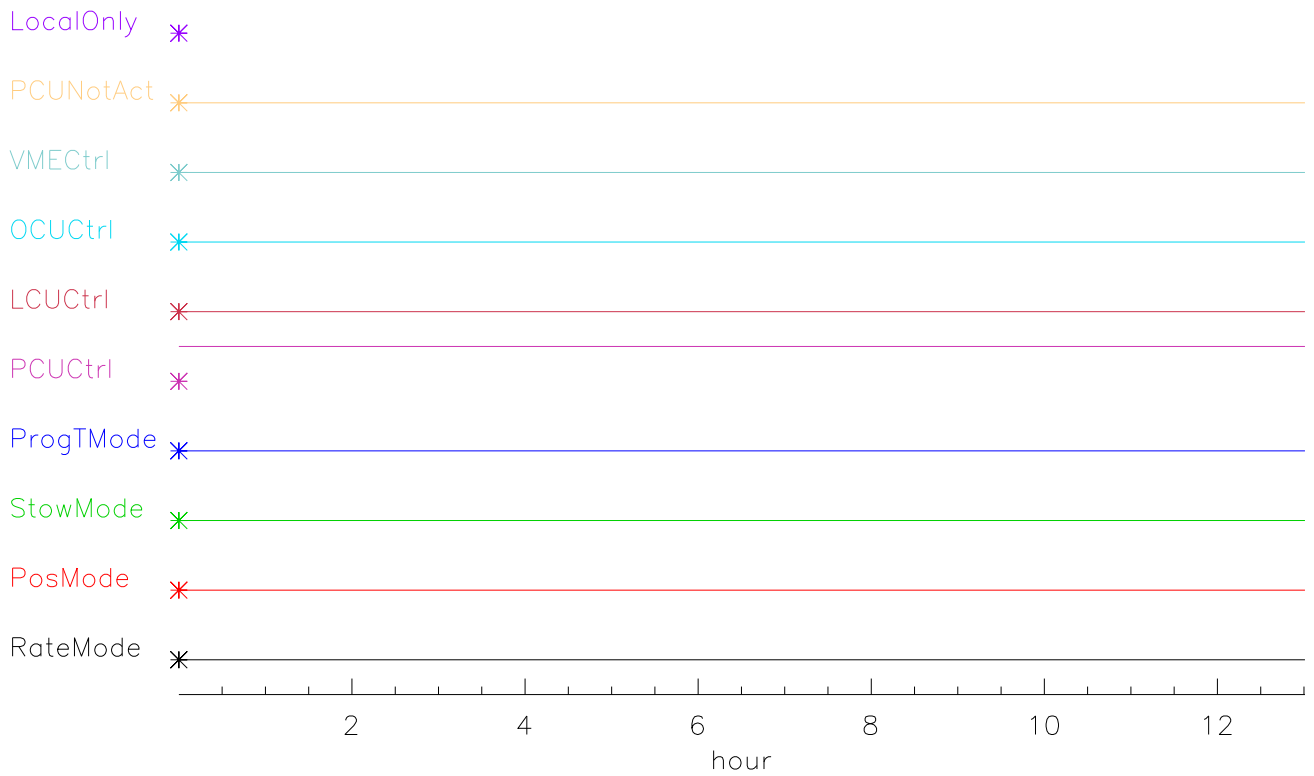
Azimuth summary for: 201103 vertex general status (page 2)



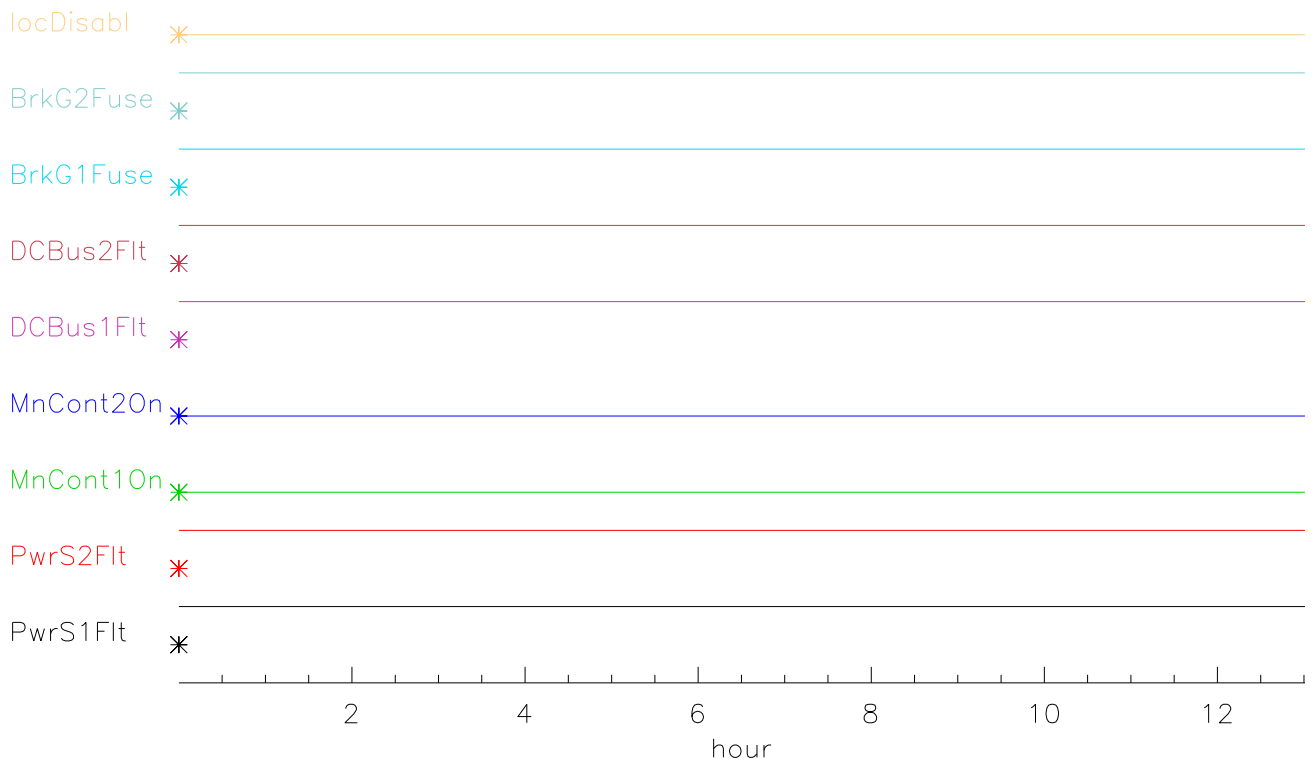
Azimuth summary for: 201103 vertex axis status (page 3)



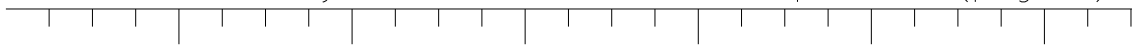
Azimuth summary for: 201103 azimuth axis mode (page 4)



Azimuth summary for: 201103 azimuth equipment status



Azimuth summary for: 201103 azimuth amp status (page 5)



Amp82NRdy*

Amp82Fit *

Amp81NRdy*

Amp81Fit *

Amp42NRdy*

Amp42Fit *

Amp41NRdy*

Amp41Fit *

Amp52NRdy*

Amp52Fit *

Amp51NRdy*

Amp51Fit *

Amp12NRdy*

Amp12Fit *

Amp11NRdy*

Amp11Fit *



2

4

6

8

10

12

hour

Azimuth summary for: 201103 azimuth motor status (page 6)

OvrTmpM82*

OvrTmpM81*

OvrTmpM42*

OvrTmpM41*

OvrTmpM52*

OvrTmpM51*

OvrTmpM12*

OvrTmpM11*



Azimuth summary for: 201103 dcs az output[8]

DCSAz: 421.0 #2 / K4 (-d_nB)

DCSAz: 421.0 #2 / K3 (d_n8)

DCSAz: 421.0 #2 / K2 (d_nB)

DCSAz: 421.0 #2 / K1 (d_n5)

DCSAz: 421.0 #1 / K4 (-d_nA)

DCSAz: 421.0 #1 / K3 (d_n4)

DCSAz: 421.0 #1 / K2 (d_nA)

DCSAz: 421.0 #1 / K1 (d_n1)



Azimuth summary for: 201103 dcs az output[9] (page 7)

DCSAz: 421_0 #4 / K4 (torque bias 81/82)

DCSAz: 421_0 #4 / K3 (tot d_n M81/82)

DCSAz: 421_0 #4 / K2 (torque bias 51/52)

DCSAz: 421_0 #4 / K1 (tot d_n M51/52)

DCSAz: 421_0 #3 / K4 (torque bias 41/42)

DCSAz: 421_0 #3 / K3 (tot d_n M41/42)

DCSAz: 421_0 #3 / K2 (torque bias 11/12)

DCSAz: 421_0 #3 / K1 (tot d_n M11/12)



Azimuth summary for: 201103 dcs az output[10]

.....*

DCS: l-portion n-loop Az on

DCS: delta_n cntrlr Az on

DCS: sum_n cntrlr Az on

DCS: torque_bias Az on

DCS: accelrmp Az fast

DCS: load setpnt Az 2

DCS: load setpnt Az 1



Azimuth summary for: 201103az Motor Torques

