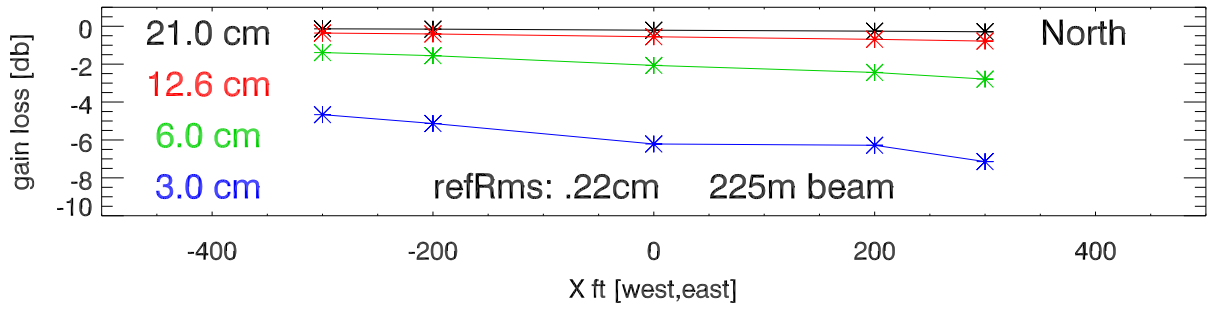
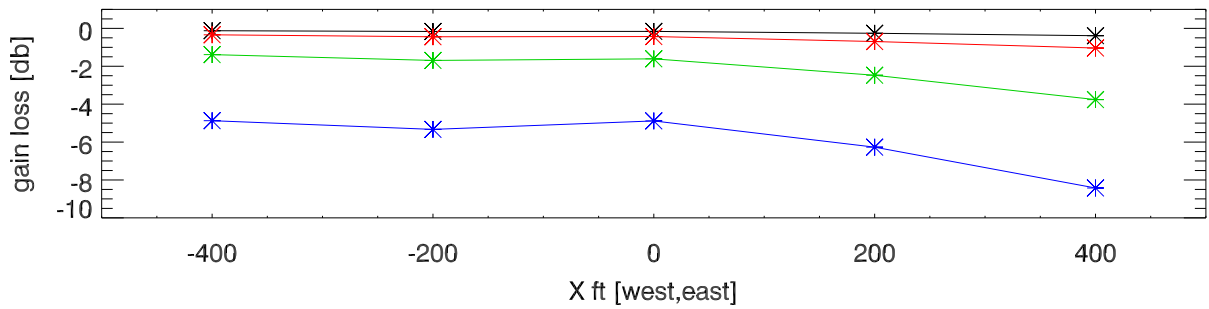


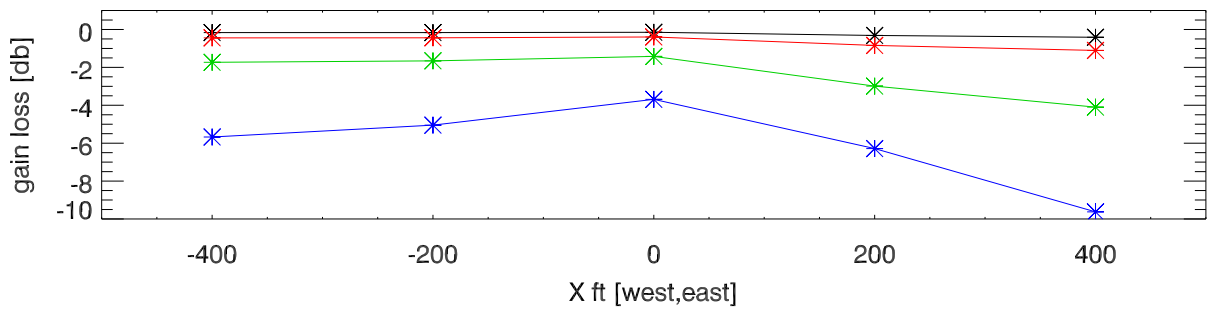
11mar20 gain loss from dish errors (<5cm) vs x,y and lambda. Y= 400 ft



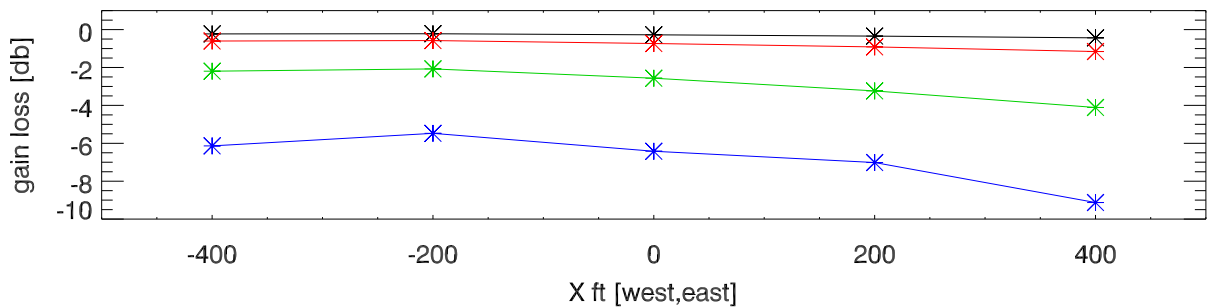
Y= 200 ft



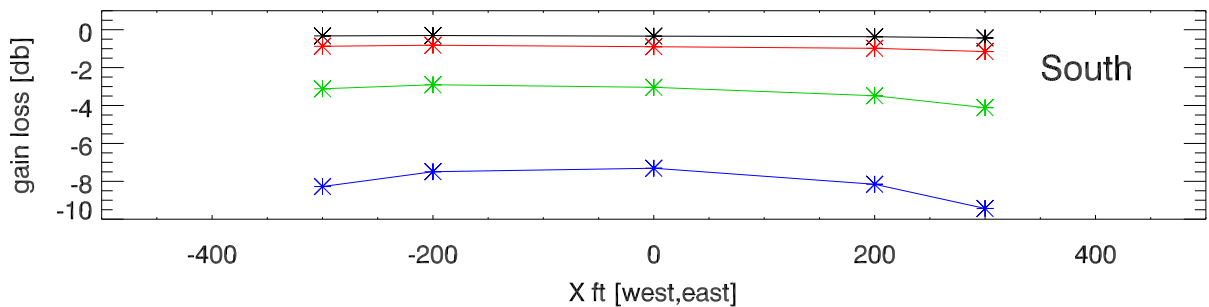
Y= 0 ft



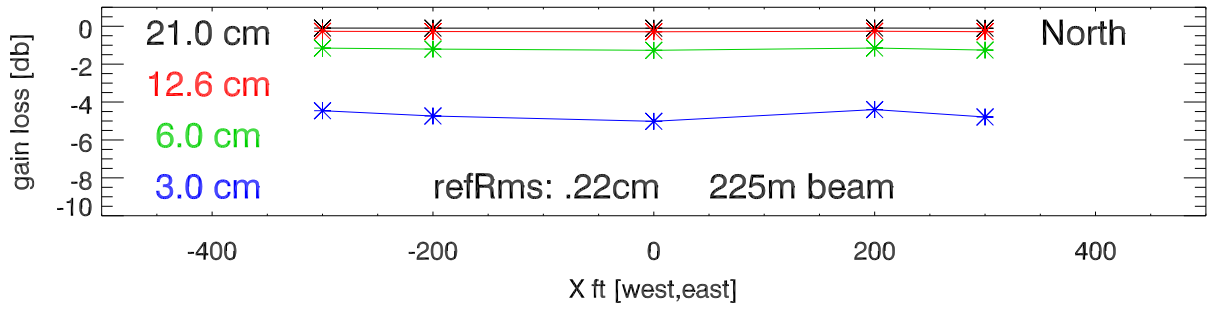
Y= -200 ft



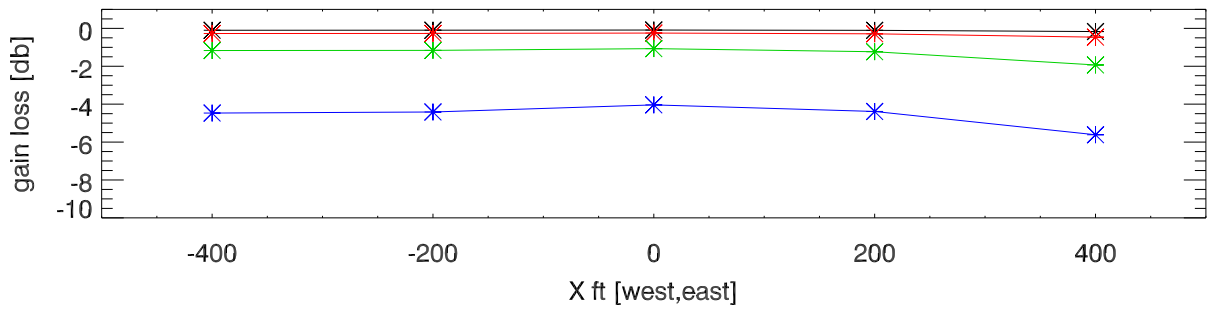
Y= -400 ft



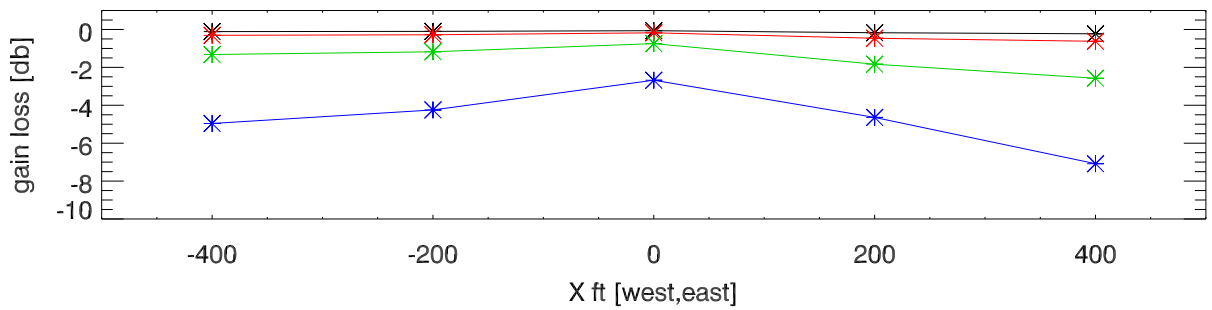
11mar20 gain loss from dish errors (<1.2cm) vs x,y and lambda. Y= 400 ft



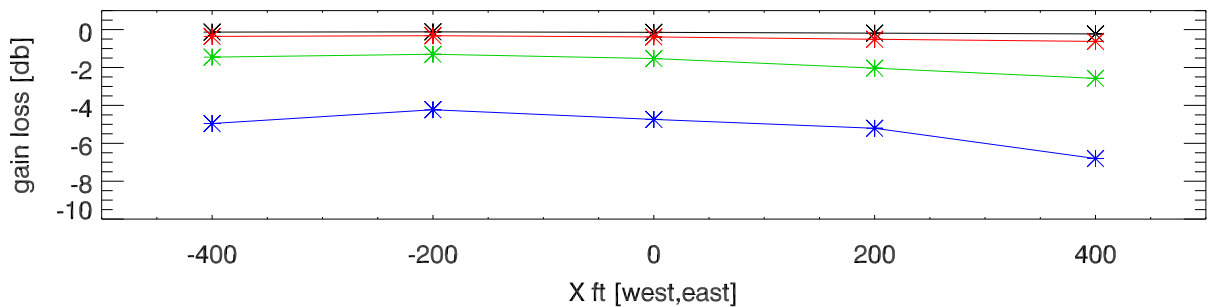
Y= 200 ft



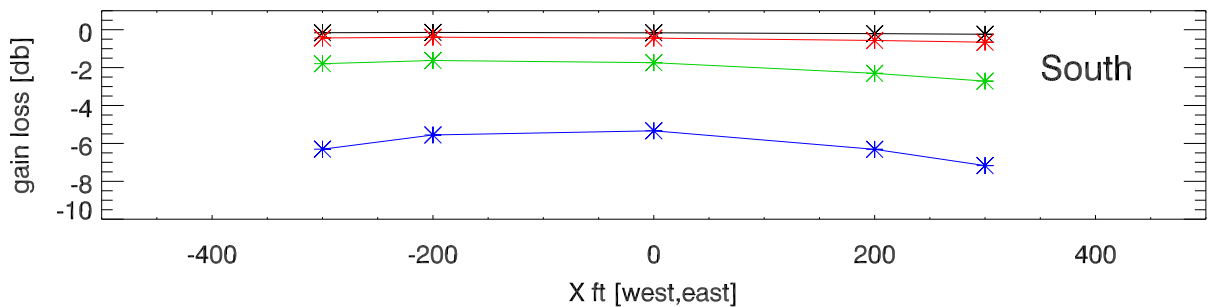
Y= 0 ft



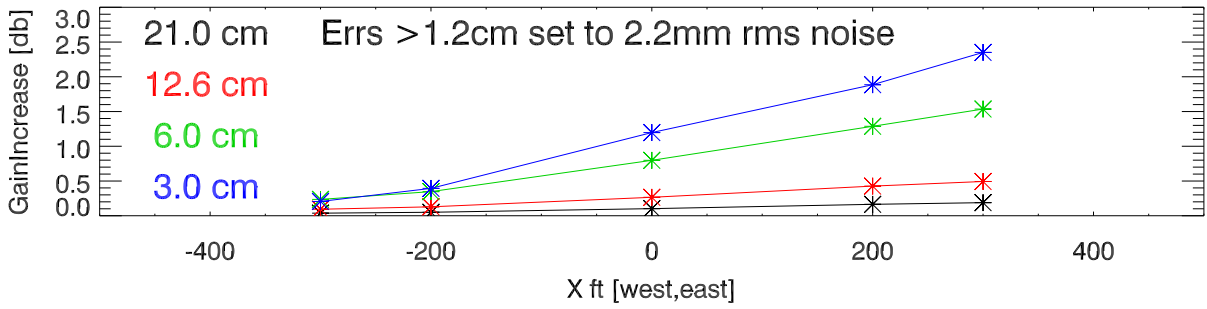
Y= -200 ft



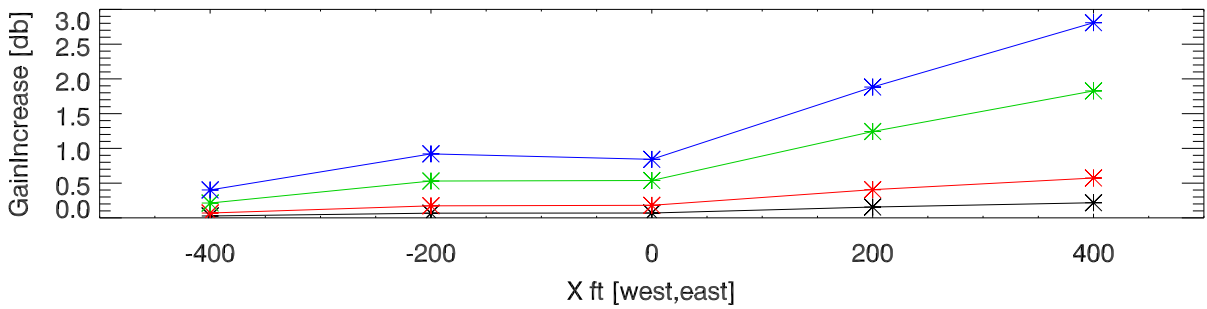
Y= -400 ft



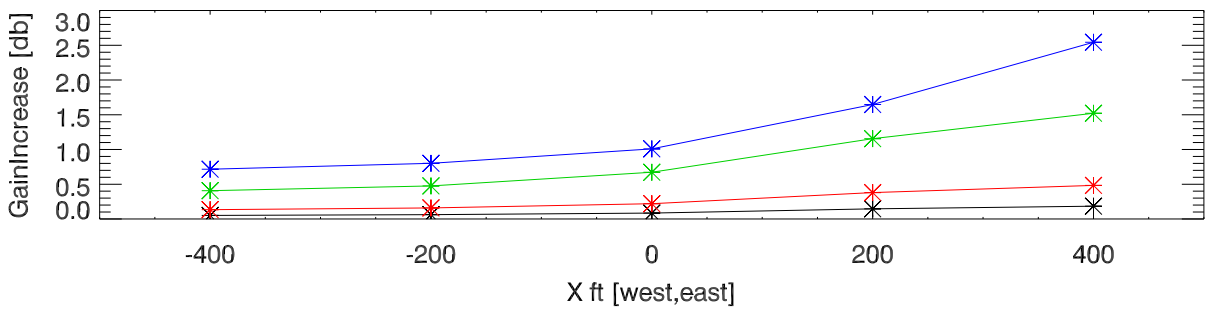
(Gain<5cmErr)/(Gain<1.2cmErr). Y= 400 ft



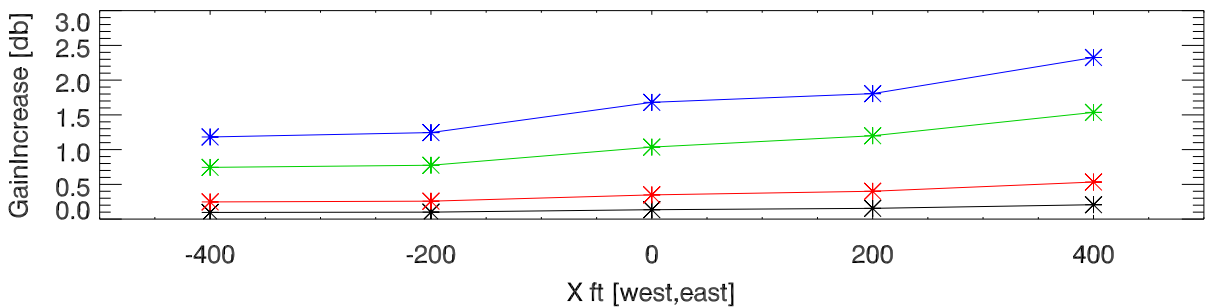
Y= 200 ft



Y= 0 ft



Y= -200 ft



Y= -400 ft

