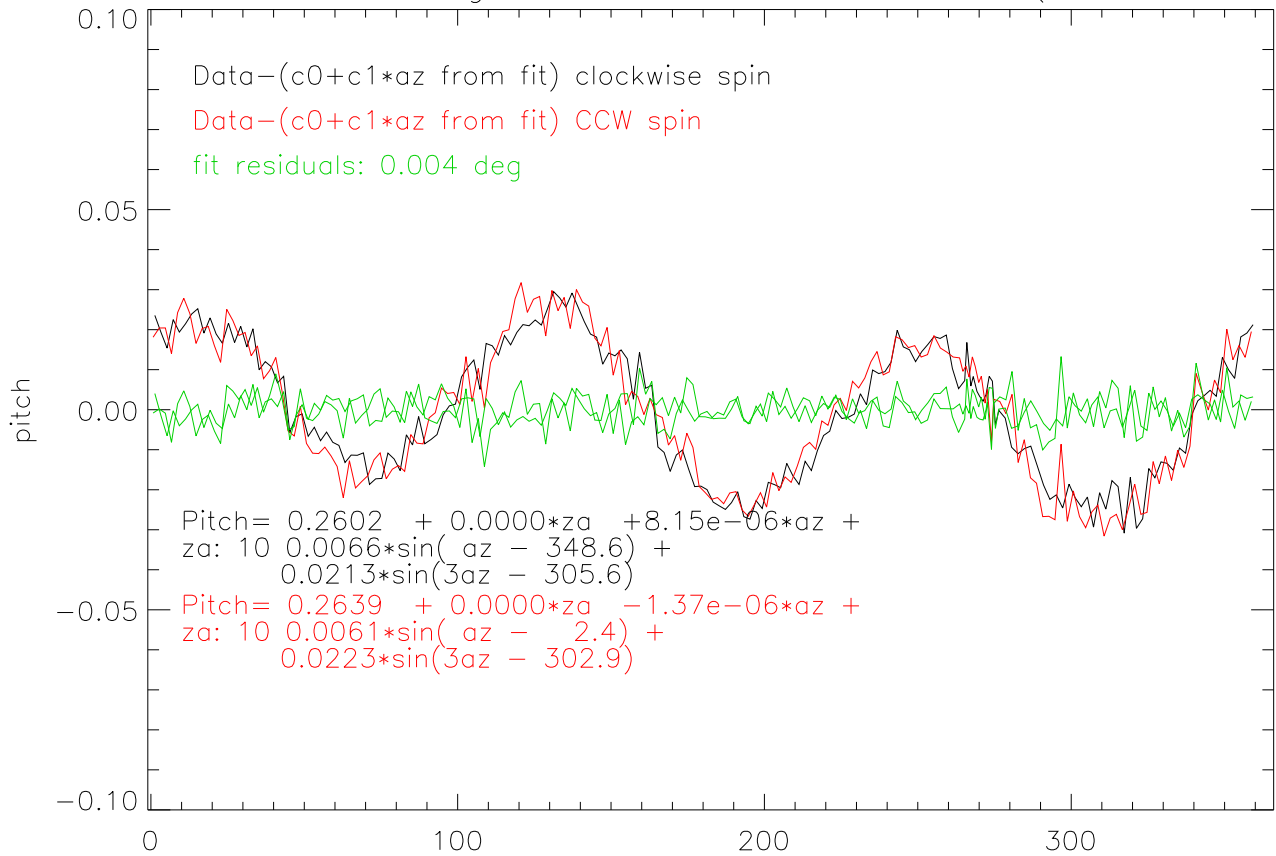


27mar07 4azsw @ 10deg za. tiltSensor frame PITCH - (c0+c1*az from fit)



27mar07 4azsw @ 10deg za. tiltSensor frame Roll - (c0+c1*az from fit)

