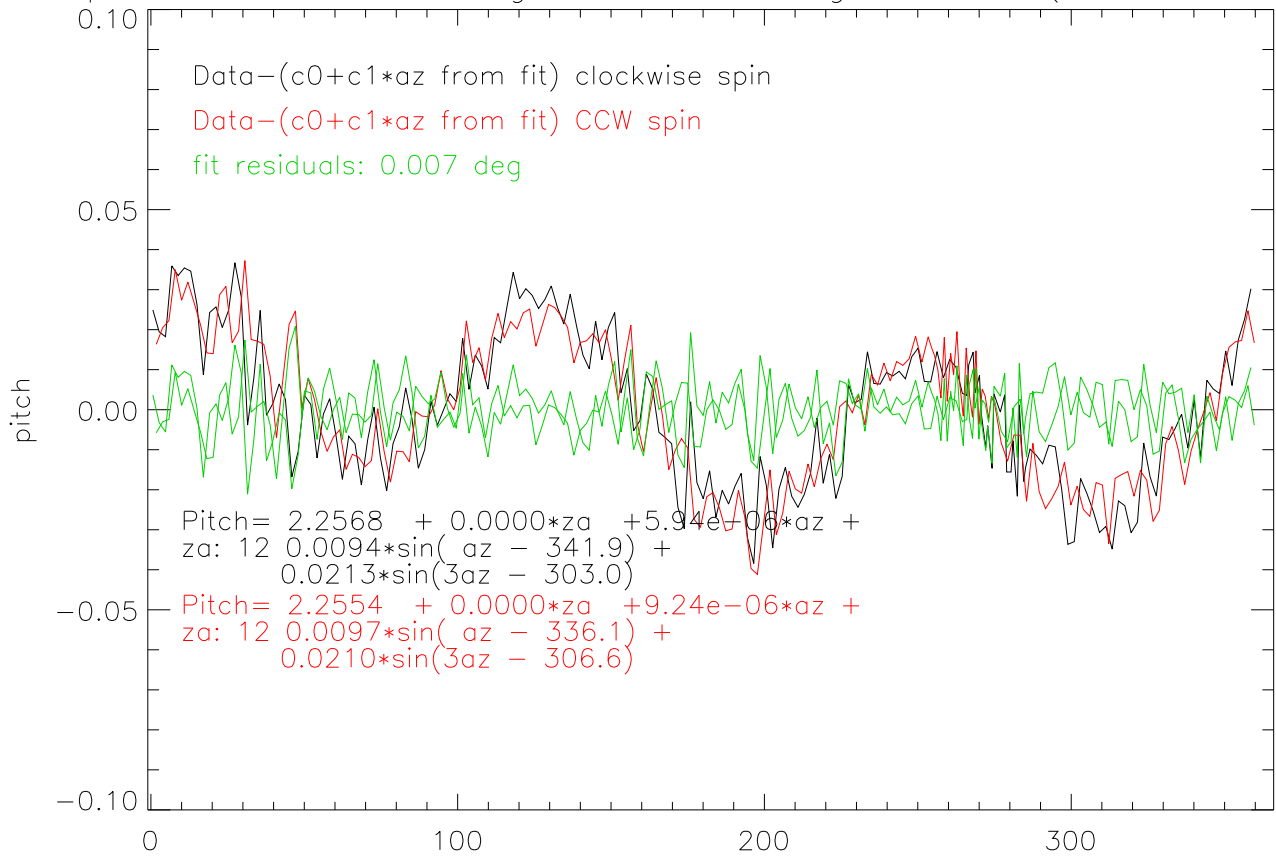


04apr07 tilt sensor az swings before td change PITCH – (c0+c1*az from fit)



04apr07 tilt sensor az swings before td change Roll – (c0+c1*az from fit)

